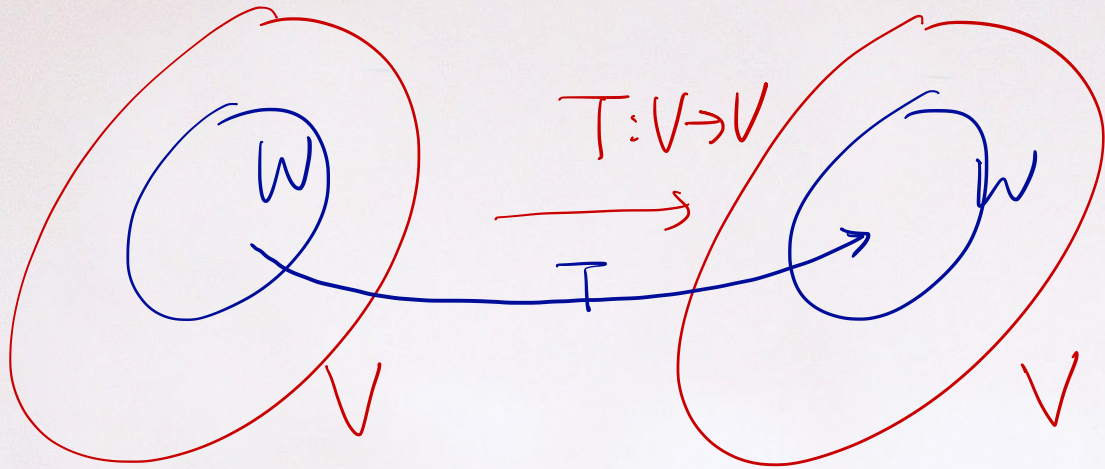


## Lecture 15:

Definition: Let  $T$  be a linear operator on a vector space  $V$ .

A subspace  $W \subset V$  is called  $T$ -invariant if  $T(W) \subseteq W$ .

That is,  $T(\vec{w}) \in W$  for  $\forall \vec{w} \in W$ .



Def:  $T|_W: W \rightarrow W$  defined by  $T|_W(\vec{w}) = T(\vec{w})$

$\mathcal{F}_{T|_W}(t)$  divides  $\mathcal{F}_T(t)$

Remark: Let  $T = V \rightarrow V$  be a linear operator on a finite-dim vector space  $V$ , and let  $W \subset V$  be a  $T$ -invariant subspace.

Then, the restriction of  $T$  to  $W$ , denote it by  $T|_W: W \rightarrow W$ , is well-defined and linear.

Proposition:  $f_{T|_W}(t)$  divides  $f_T(t)$ .

Proof: Choose an ordered basis  $\gamma = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$  for  $W$  and extend it to an ordered basis  $\beta = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k, \vec{v}_{k+1}, \dots, \vec{v}_n\}$  for  $V$ . Then:

$$[T]_{\beta} = \begin{pmatrix} \overbrace{[T|_W]_{\gamma}}^k & & \\ \vdots & \boxed{B} & \\ \vdots & & \boxed{C} \\ \vdots & & \end{pmatrix} = \begin{pmatrix} \boxed{[T|_W]_{\gamma}} & \boxed{B} \\ \bigcirc & \boxed{C} \end{pmatrix}_k$$

$$\begin{aligned}
 f_T(t) &= \det \begin{bmatrix} [T_w]_x & B \\ 0 & C \end{bmatrix} - t I \\
 &= \det \begin{pmatrix} [T_w]_x - t I_k & B \\ 0 & C - t I_{n-k} \end{pmatrix} \\
 &= \det([T_w]_x - t I_k) \underbrace{\det(C - t I_{n-k})}_{g(t)} \\
 &= f_{T_w}(t) g(t)
 \end{aligned}$$

$\therefore f_{T_w}(t)$  divides  $f_T(t)$

Theorem: Let  $T: V \rightarrow V$  be a linear operator on a finite-dim vector space  $V$  and let  $W \subset V$  be  $T$ -cyclic subspace of  $V$  generated by  $\vec{v} \neq \vec{0} \in V$ . ( $W = \text{span}\{\vec{v}, T(\vec{v}), T^2(\vec{v}), \dots\}$ )

Let  $k = \dim(W)$ . Then:

(a)  $\{\vec{v}, T(\vec{v}), T^2(\vec{v}), \dots, T^{k-1}(\vec{v})\}$  is a basis for  $W$

(b) If  $a_0 \vec{v} + a_1 T(\vec{v}) + a_2 T^2(\vec{v}) + \dots + a_{k-1} T^{k-1}(\vec{v}) + T^k(\vec{v}) = \vec{0}$ ,  
then the characteristic polynomial of  $T|_W$  is:

$$f_{T|_W}(t) = (-1)^k (a_0 + a_1 t + a_2 t^2 + \dots + a_{k-1} t^{k-1} + t^k)$$

Proof: (a) Since  $\vec{v} \neq \vec{0}$ , then  $\{\vec{v}\}$  is linearly independent.

Let  $j$  be the largest +ve integer s.t.

$\beta = \{\vec{v}, T(\vec{v}), \dots, T^{j-1}(\vec{v})\}$  is linearly independent.

Such  $j$  exists because  $V$  is finite-dim.

Let  $Z = \text{span}(\beta)$ .  $\therefore Z \subset W$

Then,  $\beta \cup T^j(\vec{v})$  is linearly dependent.  $\therefore T^j(\vec{v}) \in \text{span}(\beta)$   
L.I.  $\therefore T^j(\vec{v}) \in Z$

Now, let  $\vec{w} \in Z$ . Then  $\exists b_0, b_1, \dots, b_{j-1} \in F$  s.t.

$$\begin{aligned}\vec{w} &= b_0 \vec{v} + b_1 T(\vec{v}) + \dots + b_{j-1} T^{j-1}(\vec{v}) \\ T(\vec{w}) &= b_0 T(\vec{v}) + b_1 T^2(\vec{v}) + \dots + b_{j-2} T^{j-1}(\vec{v}) + b_{j-1} T^j(\vec{v})\end{aligned}$$

$\vec{w} \in Z$   $\in Z$   $\in Z$   $\in Z$   $\in Z$

$\therefore$  If  $\vec{w} \in Z$ , then  $T(\vec{w}) \in Z$ .

$\therefore Z$  is  $T$ -invariant containing  $\vec{v}$ .  
subspace

$\therefore \underbrace{W \subset Z}_{\text{"T-cyclic subspace containing } \vec{v}} \text{. } \left( \text{"} W \text{ is smallest } T\text{-invariant subspace containing } \vec{v} \right)$

$\therefore W = Z = \text{span}(\overbrace{\beta}^{\text{L.I.}})$

$\therefore \beta$  is a basis of  $W$  and  $j = k$ .

(b) By (a),  $\beta = \{\vec{v}, T(\vec{v}), \dots, T^{k-1}(\vec{v})\}$  is an ordered basis for  $W$ .

Let  $a_0, \dots, a_{k-1} \in F$  s.t.

$$a_0 \vec{v} + a_1 T(\vec{v}) + \dots + a_{k-1} T^{k-1}(\vec{v}) + T^k(\vec{v}) = \vec{0}$$

$$\Rightarrow T^k(\vec{v}) = -a_0 \vec{v} - a_1 T(\vec{v}) - \dots - a_{k-1} T^{k-1}(\vec{v}).$$

$$\text{Then: } [T]_{\beta} = \begin{pmatrix} | & | & & | \\ [T(\vec{v})]_{\beta} & [T(T(\vec{v}))]_{\beta} & \dots & [T^k(\vec{v})]_{\beta} \\ | & | & & | \\ 0 & 0 & \dots & 0 \\ 1 & 0 & \dots & -a_0 \\ 0 & 1 & \dots & -a_1 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \\ & & & 1 & -a_{k-1} \end{pmatrix}$$



$$f_{Tw}(t) \stackrel{\text{def}}{=} \det \left( \begin{pmatrix} 0 & 0 & \dots & 0 & -a_0 \\ 1 & \dots & 0 & \dots & -a_1 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & 0 & \dots & 0 & -a_{k-1} \end{pmatrix} - \lambda I_k \right)$$

$$(-1)^k (a_0 + a_1 t + \dots + a_{k-1} t^{k-1} + t^k) \quad (\text{HW})$$

Theorem: (Cayley - Hamilton) Let  $T$  be a linear operator on a finite-dim. vector space  $V$  and let  $f(t) = f_T(t)$  be a char poly of  $T$ . Then:  $f(T) = \text{zero transformation}$ .  
(Char poly "kills" the linear operator  $T$ )

Remark:  $f(t) = a_0 1 + a_1 t + a_2 t^2 + \dots + a_n t^n$   
 $f(T) = a_0 I + a_1 T + a_2 T^2 + \dots + a_n T^n$

Proof: We want to show  $f(T)(\vec{v}) = \vec{0}$  for all  $\vec{v} \in V$ .

$$f(T)(\vec{0}) = \vec{0} \quad (\because f(T) \text{ is linear})$$

So, suppose  $\vec{v} \neq \vec{0}$ . Let  $W = T$ -cyclic subspace generated by  $\vec{v}$ .

$$\text{Let } k = \dim(W)$$

By Thm we have shown last time:

$\exists a_0, a_1, \dots, a_{k-1} \in F$  such that:

$$\left\{ \begin{array}{l} \cdot a_0 \vec{v} + a_1 T(\vec{v}) + \dots + a_{k-1} T^{k-1}(\vec{v}) + T^k(\vec{v}) = \vec{0} \\ \cdot g(t) \stackrel{\text{def}}{=} f_{T|_W} = (-1)^k (a_0 + a_1 t + \dots + a_{k-1} t^{k-1} + t^k) \end{array} \right.$$

$$\left\{ \begin{array}{l} \cdot a_0 \vec{v} + a_1 T(\vec{v}) + \dots + a_{k-1} T^{k-1}(\vec{v}) + T^k(\vec{v}) = \vec{0} \\ \cdot g(t) \stackrel{\text{def}}{=} f_{T|W} = (-1)^k (a_0 + a_1 t + \dots + a_{k-1} t^{k-1} + t^k) \end{array} \right.$$

$$g(T)(\vec{v}) = \vec{0}$$

Now,  $g(t) \mid f(t) \stackrel{\text{implies}}{\rightsquigarrow} \exists g(t) \text{ s.t. } f(t) = g(t)g(t)$

$$\therefore f(T)(\vec{v}) = g(T) \cdot g(T)(\vec{v}) = \vec{0}$$

$$f(T) = g(T)g(T) \uparrow g(T) \cdot g(T)$$

Corollary: Let  $A \in M_{n \times n}(F)$  and  $f(t)$  be its char. poly. Then :  $f(A) = O$ , the zero matrix.

## Tensor Product Space

Definition: A map  $B: X \times Y \rightarrow Z$  ( $X, Y, Z$  are vector spaces over  $F$ ) is a bilinear map if:

$$B(a\vec{u} + b\vec{v}, c\vec{s} + d\vec{t}) = ac B(\vec{u}, \vec{s}) + ad B(\vec{u}, \vec{t}) + bc B(\vec{v}, \vec{s}) + bd B(\vec{v}, \vec{t})$$

where  $\vec{u}, \vec{v} \in X$ ,  $\vec{s}, \vec{t} \in Y$ ,  $a, b, c, d \in F$ .

Definition: Let  $V_1, V_2$  be vector spaces over  $F$ . A pair  $(Y, \mu)$ , where  $Y$  is a vector space over  $F$  and  $\mu: V_1 \times V_2 \rightarrow Y$  is a bi-linear map, is called the tensor product of  $V_1$  and  $V_2$  if the following condition holds:

(\*) whenever  $\beta_1$  is a basis for  $V_1$  and  $\beta_2$  is a basis for  $V_2$ , then:

$\mu(\beta_1 \times \beta_2) \stackrel{\text{def}}{=} \{ \mu(\vec{x}_1, \vec{x}_2) : \vec{x}_1 \in \beta_1, \vec{x}_2 \in \beta_2 \}$  is a basis for  $Y$ .

Remark: We write  $V_1 \otimes V_2$  for  $Y$ .

We write  $\vec{x}_1 \otimes \vec{x}_2$  for  $\mu(\vec{x}_1, \vec{x}_2)$ .